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Note	$\mathcal{P}(A) = \{\text{all the subsets of } A\}$.
Remark	$\text{card } A = n \Rightarrow \text{card } \mathcal{P}(A) = 2^n$.
Note	$\mathcal{P}(A) = \{\emptyset, \{a_1\}, \{a_2\}, \{a_3\}, \dots\}$ so single elements sets in $\mathcal{P}(A)$ are equal in number to the number of elements of A .
Note	$A \subseteq B \Rightarrow \text{card } A \leq \text{card } B \Rightarrow \exists f: A \rightarrow B$ that is 1-1, or equivalently, $\exists g: B \rightarrow A$ that is onto.

Theorem $\text{card } A < \text{card } \mathcal{P}(A)$.

Proof:

Suppose $\text{card } A \geq \text{card } \mathcal{P}(A)$. Then $\exists f: A \rightarrow \mathcal{P}(A)$ that is onto. Consider $A_1 = \{a \in A : a \notin f(a)\}$. Note that $A_1 \subseteq A$, hence $A_1 \in \mathcal{P}(A)$. Since f is onto and $A_1 \in \mathcal{P}(A)$, then $\exists a_1 \in A$ such that $f(a_1) = A_1$. Since $A_1 \subseteq A$, then $a_1 \in A_1$, or $a_1 \notin A_1$. If $a_1 \in A_1$, then $a_1 \notin f(a_1)$, but $f(a_1) = A_1$, so $a_1 \notin A_1$. $\Rightarrow \Leftarrow$ If $a_1 \notin A_1$, then $a_1 \in f(a_1) = A_1$. $\Rightarrow \Leftarrow$ $\therefore f$ is not onto. $\therefore \text{card } A \neq \text{card } \mathcal{P}(A)$, hence $\text{card } A < \text{card } \mathcal{P}(A)$.

Note $\text{card } \mathbb{N} = \aleph_0$, $\text{card } \mathbb{R} = \mathfrak{C}_1$, $\text{card } \mathcal{P}(\mathbb{R}) = \mathfrak{C}_2$.

Metric Spaces

Definition 2.15 Consider a non-empty set X . A function $d: X \times X \rightarrow \mathbb{R}$ is called a *metric* if

Positivity (a) $d(x, y) \geq 0 \forall x, y \in X$; $d(x, y) = 0 \Leftrightarrow x = y$.

Symmetry (b) $d(x, y) = d(y, x) \forall x, y \in X$.

Triangle Inequality (c) $d(x, y) \leq d(x, z) + d(z, y) \forall x, y, z \in X$.

Note If we replace $d(x, y) = 0 \Leftrightarrow x = y$ with $d(x, x) = 0 \forall x \in X$, we have a semi-metric.

Example In \mathbb{R}^2 , define $d((x_1, x_2), (y_1, y_2)) = |x_1 - y_1|$. This is a semi-metric.

But we can fix this by defining equivalence classes.

Define $x \sim y \Leftrightarrow d(x, y) = 0$.

This is an equivalence relation:

$$\begin{aligned} x &\sim x. \\ x \sim y &\Rightarrow y \sim x. \\ x \sim y \text{ and } y \sim z &\Rightarrow x \sim z. \end{aligned}$$

So then $x/\sim = \{[x] : x \in X\}$.

And this gives us $d([x], [y]) = 0 \Leftrightarrow [x] = [y]$.

Question How does the norm relate to the metric?

Every norm defines $d(x, y) = |x - y|$.

So *every norm space is also a metric space*.

Is the reverse true?

No. Metric spaces don't require any algebraic structure on the space, yet norm spaces do. A metric space can be simply a set of points with measurable distances between them. But recall that $\|x\|_p = (\sum |x_i|^p)^{1/p}$. So *not all metric spaces are norm spaces*.

Definition 2.18

Let (X, d) be a metric space.

(a) A *neighborhood* (ball) centered at a point x of positive radius $r \in \mathbb{R}$, denoted $N_r(x) = \{y \in X \mid d(x, y) < r\}$.

(b) $x_0 \in X$ is a *limit point* of E if $\forall r > 0, N_r(x_0) \cap \{E \setminus \{x_0\}\} \neq \emptyset$.

Or equivalently, $\exists y \in E$ such that $y \neq x_0$ and $y \in N_r(x_0)$, i.e. $d(x, y) < r$.

Note

Theorem 2.20 relates to the definition of limit point.

See proof below.

(c) If $x \in E$ is not a limit point of E , then x is an *isolated point* of E .

Or, equivalently, $\exists r > 0$ such that $N_r(x_0) \cap \{E \setminus \{x_0\}\} = \emptyset$.

Example

$E = (0, 1) \cup \{2\}$. 2 is an isolated point of E .

(d) $E \subset X$ is *closed* if every limit point of E belongs to E .

(e) $x \in E$ is an *interior point* of E if $\exists r > 0$ such that $N_r(x) \subset E$.

(f) $E \subset X$ is *open* if every point of E is an interior point of E .

Note

E is open $\Leftrightarrow X \setminus E$ is closed. And E is closed $\Leftrightarrow X \setminus E$ is open.

Theorem

2.20 If p is a limit point of a set E , then every neighborhood of p contains infinitely many points of E .

Sketch of proof (informal):

Let $r > 0$.

By the definition of limit point

$\exists x_1 \neq x_0$ where $x_1 \in N_r(x_0)$.

By the definition again

$\exists x_2 \neq x_0$ where $x_2 \in N_{x_0-x_1}(x_0)$.

We continue this infinitely many times to find infinitely many points in $N_r(x_0)$.

See diagram.

